## EE 150 - Applications of Convex Optimization in Signal Processing and Communications Dr. Andre Tkacenko, JPL Third Term 2011-2012

## Homework Set #4

Due on **Thursday, May 3** in class.

- 1. (10 points) (Adapted from CO-BV, Exercise 3.49) (*Log-concave functions:*) Show that the following functions are log-concave.
  - (a) Logistic function:

$$f(x) = \frac{e^x}{1 + e^x}, \ \dim(f(x)) = \mathbb{R}.$$

(b) Harmonic mean:

$$f(\mathbf{x}) = \frac{1}{\frac{1}{x_1} + \dots + \frac{1}{x_n}}, \text{ dom}(f(\mathbf{x})) = \mathbb{R}^n_{++}.$$

(c) Product over sum:

$$f(\mathbf{x}) = \frac{\prod_{k=1}^{n} x_k}{\sum_{k=1}^{n} x_k}, \text{ dom}(f(\mathbf{x})) = \mathbb{R}_{++}^n.$$

(d) Determinant over trace:

$$f(\mathbf{X}) = \frac{\det(\mathbf{X})}{\operatorname{tr}(\mathbf{X})}, \ \operatorname{dom}(f(\mathbf{X})) = \mathbb{S}_{++}^n$$

*Hint:* The *Cauchy-Schwarz inequality* may be useful here, which states that for any inner product  $\langle \cdot, \cdot \rangle$ , we have

$$\left|\langle \mathbf{x}, \mathbf{y} 
ight
angle 
ight|^2 \leq \langle \mathbf{x}, \mathbf{x} 
angle \cdot \langle \mathbf{y}, \mathbf{y} 
angle \; ,$$

with equality if and only if  $\mathbf{x}$  and  $\mathbf{y}$  are linearly dependent, which is equivalent to saying that either  $\mathbf{y} = C\mathbf{x}$  or  $\mathbf{x} = C\mathbf{y}$  for some  $C \in \mathbb{F}$ .

- 2. (10 points) (Adapted from CO-BV, Exercise 4.7) (*Convex-affine/convex-concave fractional functions:*)
  - (a) Convex-affine fractional functions: Consider a problem of the following form:

minimize 
$$\frac{f_0(\mathbf{x})}{\mathbf{c}^T \mathbf{x} + d}$$
  
subject to  $f_k(\mathbf{x}) \le 0, \ k = 1, \dots, m$ ,  
 $\mathbf{A}\mathbf{x} = \mathbf{b}$ 

where  $f_0(\mathbf{x})$ ,  $\mathbf{f}_1(\mathbf{x})$ ,...,  $f_m(\mathbf{x})$  are convex, and the domain of the objective function is defined as  $\{\mathbf{x} \in \text{dom}(f_0(\mathbf{x})) : \mathbf{c}^T \mathbf{x} + d > 0\}$ .

i. Show that this is a quasiconvex optimization problem.

ii. Show that the problem is equivalent to

minimize 
$$g_0(\mathbf{y}, t)$$
  
subject to  $g_k(\mathbf{y}, t) \le 0, \ k = 1, \dots, m$   
 $\mathbf{A}\mathbf{y} = \mathbf{b}t$ ,  
 $\mathbf{c}^T\mathbf{y} + td = 1$ 

where  $g_k(\mathbf{x}, t)$  is the perspective of  $f_k(\mathbf{x})$ , i.e.,  $g_k(\mathbf{x}, t) = t f_k(\mathbf{x}/t)$ . The variables are  $\mathbf{y} \in \mathbb{R}^n$  and  $t \in \mathbb{R}$ . Show that this problem is convex.

(b) *Convex-concave fractional functions:* Analogous to the problem analyzed above, consider a problem of the form:

$$\begin{array}{ll} \text{minimize} & \displaystyle \frac{f_0(\mathbf{x})}{h(\mathbf{x})} \\ \text{subject to} & \displaystyle f_k(\mathbf{x}) \leq 0 \,, \ k=1,\ldots,m \end{array}, \\ & \mathbf{A}\mathbf{x} = \mathbf{b} \end{array}$$

where  $f_0(\mathbf{x}), \mathbf{f}_1(\mathbf{x}), \ldots, f_m(\mathbf{x})$  are convex,  $h(\mathbf{x})$  is concave, and the domain of the objective function is defined as  $\{\mathbf{x} \in \text{dom}(f_0(\mathbf{x})) \cap \text{dom}(h(\mathbf{x})) : h(\mathbf{x}) > 0\}$  and  $f_0(\mathbf{x}) \ge 0$  everywhere.

- i. Show that this is a quasiconvex optimization problem.
- ii. Show that the problem is equivalent to

minimize 
$$g_0(\mathbf{y}, t)$$
  
subject to  $g_k(\mathbf{y}, t) \le 0, \ k = 1, \dots, m$   
 $\mathbf{A}\mathbf{y} = \mathbf{b}t$   
 $\widetilde{h}(\mathbf{y}, t) \le -1$ 

,

where  $g_k(\mathbf{x}, t)$  is the perspective of  $f_k(\mathbf{x})$  and  $\tilde{h}(\mathbf{x}, t)$  is the perspective of  $-h(\mathbf{x})$ . Show that this problem is convex.

iii. As an example, apply the technique derived in the previous part to the unconstrained problem with

$$f_0(\mathbf{x}) = \frac{1}{m} \operatorname{tr}(\mathbf{F}(\mathbf{x})) , \ h(\mathbf{x}) = (\operatorname{det}(\mathbf{F}(\mathbf{x})))^{\frac{1}{m}} ,$$

with dom $\left(\frac{f_0(\mathbf{x})}{h(\mathbf{x})}\right) = {\mathbf{x} : \mathbf{F}(\mathbf{x}) \succ \mathbf{0}}$ , where  $\mathbf{F}(\mathbf{x}) = \mathbf{F}_0 + x_1 \mathbf{F}_1 + \dots + x_n \mathbf{F}_n$  for given  $\mathbf{F}_k \in \mathbb{S}^m$ . In this problem, we minimize the ratio of the arithmetic mean over the geometric mean of the eigenvalues of an affine matrix function  $\mathbf{F}(\mathbf{x})$ .

**3.** (10 points) (Adapted from CO-BV, Exercise 4.24) (*Complex*  $\ell_1$ - $\ell_2$ -, and  $\ell_{\infty}$ -norm approximation:) Consider the problem

minimize 
$$||\mathbf{A}\mathbf{x} - \mathbf{b}||_p$$
,

where  $\mathbf{A} \in \mathbb{C}^{m \times n}$ ,  $\mathbf{b} \in \mathbb{C}^m$ , and the variable is  $\mathbf{x} \in \mathbb{C}^n$ . Recall that the (real or complex)  $\ell_p$ -norm is defined by

$$||\mathbf{y}||_{p} \triangleq \left(\sum_{k=1}^{m} |y_{k}|^{p}\right)^{\frac{1}{p}}$$

for  $p \ge 1$ , and  $||\mathbf{y}||_{\infty} = \max_{k=1,\dots,m} |y_k|$ . For p = 1, 2, and  $\infty$ , express the complex  $\ell_p$ -norm approximation problem as a *second-order cone program* (SOCP) or *quadratically constrained quadratic program* (QCQP) with real variables and data.

4. (10 points) (Adapted from CO-AE, Exercise 3.11) (Using Schur complements to express matrix-based optimization problems as semidefinite programs:) Formulate each of the following optimization problems as a semidefinite program (SDP). The variable is  $\mathbf{x} \in \mathbb{R}^n$  and the function  $\mathbf{F}(\mathbf{x})$  is defined as

$$\mathbf{F}(\mathbf{x}) = \mathbf{F}_0 + x_1 \mathbf{F}_1 + \dots + x_n \mathbf{F}_n,$$

with  $\mathbf{F}_k \in \mathbb{S}^m$ . The domain of  $f(\mathbf{x})$  in each subproblem is  $\operatorname{dom}(f(\mathbf{x})) = \{\mathbf{x} \in \mathbb{R}^n : \mathbf{F}(\mathbf{x}) \succ \mathbf{0}\}.$ 

- (a) Minimize  $f(\mathbf{x}) = \mathbf{c}^T (\mathbf{F}(\mathbf{x}))^{-1} \mathbf{c}$ , where  $\mathbf{c} \in \mathbb{R}^m$ .
- (b) Minimize  $f(\mathbf{x}) = \max_{k=1,\dots,K} \mathbf{c}_k^T (\mathbf{F}(\mathbf{x}))^{-1} \mathbf{c}_k$ , where  $\mathbf{c}_k \in \mathbb{R}^m$  for  $k = 1,\dots,K$ .
- (c) Minimize  $f(\mathbf{x}) = \sup_{||\mathbf{c}||_2 \leq 1} \mathbf{c}^T (\mathbf{F}(\mathbf{x}))^{-1} \mathbf{c}.$
- (d) Minimize  $f(\mathbf{x}) = E\left[\mathbf{c}^T (\mathbf{F}(\mathbf{x}))^{-1} \mathbf{c}\right]$ , where **c** is a random vector with mean  $\overline{\mathbf{c}} = E[\mathbf{c}]$ and covariance  $\mathbf{S} = E\left[(\mathbf{c} - \overline{\mathbf{c}}) (\mathbf{c} - \overline{\mathbf{c}})^T\right]$ . Assume here that the covariance matrix has the following representation:  $\mathbf{S} = \sum_{k=1}^m \mathbf{s}_k \mathbf{s}_k^T$ , where  $\mathbf{s}_k \in \mathbb{R}^m$  for  $k = 1, \dots, m$ .
- \*5. (30 points) (Adapted from CO-AE, Exercise 2.19) (Majorization and symmetric functions of eigenvalues:) Here, we use x<sub>[k]</sub> to denote the k-th largest element of a vector x ∈ ℝ<sup>n</sup>. Thus, x<sub>[1]</sub>, x<sub>[2]</sub>,..., x<sub>[n]</sub> are the elements of x sorted in decreasing order. We say that a vector y ∈ ℝ<sup>n</sup> majorizes a vector x ∈ ℝ<sup>n</sup> if

$$\begin{array}{rcl} \mathbf{y}_{[1]} & \geq & \mathbf{x}_{[1]} \,, \\ & \mathbf{y}_{[1]} + \mathbf{y}_{[2]} & \geq & \mathbf{x}_{[1]} + \mathbf{x}_{[2]} \,, \\ & \mathbf{y}_{[1]} + \mathbf{y}_{[2]} + \mathbf{y}_{[3]} & \geq & \mathbf{x}_{[1]} + \mathbf{x}_{[2]} + \mathbf{x}_{[3]} \,, \\ & & \vdots \\ & & & \\ \mathbf{y}_{[1]} + \mathbf{y}_{[2]} + \dots + \mathbf{y}_{[n-1]} & \geq & \mathbf{x}_{[1]} + \mathbf{x}_{[2]} + \dots + \mathbf{x}_{[n-1]} \,, \\ & & \mathbf{y}_{[1]} + \mathbf{y}_{[2]} + \dots + \mathbf{y}_{[n]} & = & \mathbf{x}_{[1]} + \mathbf{x}_{[2]} + \dots + \mathbf{x}_{[n]} \,. \end{array}$$

In other words, the descending-ordered partial sums of  $\mathbf{y}$  are greater than or equal to those of  $\mathbf{x}$  and the sum of the components of  $\mathbf{y}$  and  $\mathbf{x}$  are equal.

(a) It can be shown that  $\mathbf{y}$  majorizes  $\mathbf{x}$  if and only if there exists a *doubly stochastic matrix*  $\mathbf{P}$  such that  $\mathbf{x} = \mathbf{P}\mathbf{y}$ . A doubly stochastic matrix is one with nonnegative entries whose rows and columns add up to unity:

$$P_{k,\ell} \ge 0, \ k, \ell = 1, \dots, n, \ \mathbf{P1} = \mathbf{1}, \ \mathbf{1}^T \mathbf{P} = \mathbf{1}^T$$

Use this characterization to show the following: if  $f : \mathbb{R} \to \mathbb{R}$  is a convex function and **y** majorizes **x**, then

$$\sum_{k=1}^{n} f(y_k) \ge \sum_{k=1}^{n} f(x_k) \; .$$

(b) We use the notation  $\lambda_k(\mathbf{X})$  to denote the k-th largest eigenvalue of a matrix  $\mathbf{X} \in \mathbb{S}^n$ , so that  $\lambda_1(\mathbf{X}), \ldots, \lambda_n(\mathbf{X})$  are the eigenvalues of  $\mathbf{X}$  sorted in decreasing order. Let r be any integer in the set  $\{1, \ldots, n\}$ . Show that

$$\lambda_1(\mathbf{X}) + \dots + \lambda_r(\mathbf{X}) = \sup \left\{ \operatorname{tr}(\mathbf{X}\mathbf{Z}) : \mathbf{Z} \in \mathbb{S}^n, \ \mathbf{0} \leq \mathbf{Z} \leq \mathbf{I}, \ \operatorname{tr}(\mathbf{Z}) = r \right\}.$$
(1)

What does this tell us about the convexity properties of the function  $g_r(\mathbf{X}) = \lambda_1(\mathbf{X}) + \cdots + \lambda_r(\mathbf{X})$  (i.e., the sum of the largest r eigenvalues of  $\mathbf{X}$ )?

*Hint:* Show that the right-hand side of (1) is equal to the left-hand side by using an eigenvalue decomposition of  $\mathbf{X}$  to reduce the maximization in (1) to a simple linear program whose solution is the sum of the r largest eigenvalues of  $\mathbf{X}$ .

(c) Let  $\mathbf{X} = \theta \mathbf{U} + (1 - \theta) \mathbf{V}$  be a convex combination of two matrices  $\mathbf{U}, \mathbf{V} \in \mathbb{S}^n$ . Use the results of the previous part to show that the vector

$$\mathbf{a} \triangleq \theta \begin{bmatrix} \lambda_1(\mathbf{U}) \\ \vdots \\ \lambda_n(\mathbf{U}) \end{bmatrix} + (1-\theta) \begin{bmatrix} \lambda_1(\mathbf{V}) \\ \vdots \\ \lambda_n(\mathbf{V}) \end{bmatrix}$$

majorizes the vector  $\mathbf{b} \triangleq \begin{bmatrix} \lambda_1(\mathbf{X}) & \cdots & \lambda_n(\mathbf{X}) \end{bmatrix}^T$ .

(d) Combine the results of parts (a) and (c) to show that if  $f : \mathbb{R} \to \mathbb{R}$  is convex, then the function  $h : \mathbb{S}^n \to \mathbb{R}$  defined as

$$h(\mathbf{X}) = \sum_{k=1}^{n} f(\lambda_k(\mathbf{X}))$$

is convex.

For example, by taking  $f(x) = x \log(x)$ , we can conclude that the function  $h(\mathbf{X}) = \sum_{k=1}^{n} \lambda_k(\mathbf{X}) \log(\lambda_k(\mathbf{X}))$  is convex on  $\mathbb{S}_{++}^n$ . This function arises in quantum information theory where it is known as the (negative) Von Neumann entropy. When  $\mathbf{X}$ is diagonal, i.e.,  $\mathbf{X} = \operatorname{diag}(\mathbf{x})$ , it reduces to the negative Shannon entropy  $\sum x_k \log x_k$ .

## **Reading assignments:**

1. Read through Chapter 3 and begin Chapter 4 of CO-BV.

## **Reminders:**

*Late homework policy for EE 150:* Late homeworks will not be accepted. There will be no exceptions to this other than institute established emergency reasons, in which case a signed letter is required from an authorized official.

NCT Problems: Remember that problems with an asterisk, such as \*7 are no collaboration type

(NCT) problems.

**Texts:** The abbreviation CO-BV corresponds to the textbook "Convex Optimization" by Stephen Boyd and Lieven Vandenberghe. In addition, CO-AE refers to the Additional Exercises for Convex Optimization, also by Boyd and Vandenberghe. Finally, CVX corresponds to the cvx Users' Guide by Michael Grant and Stephen Boyd.